

**SERVO-TOP**  
**QE5542**

**CE**

**TYPE**  
**QP40SE**

**Instruction Manual**

**Part 3**

QUICK-ROTAN Elektromotoren GmbH  
Königstraße 154  
D-67655 Kaiserslautern  
Tel.: 0631 / 200 38 80  
Fax: 0631 / 200 38 62  
E-Mail: tech.supp@quick-rotan.com  
www.quick-rotan.com

[www.promelectroaytomat.ru](http://www.promelectroaytomat.ru)  
English 2002-09-20

## **Contents**

**Page**

### **Part 3**

<b>11.</b>	Survey and List of Parameters	11.1 - 11.7
11.1	Explanation of Parameter Survey	
11.2	Explanation of Parameter List	
11.3	Parameter Survey - P40SE	
11.4	List of Parameters - P40SE	
<b>12.</b>	Electrical Connections Diagram P40SE	12.1 - 12.3
<b>13.</b>	Maintenance and Repair	13.1

**Technical updatings reserved!**

## 11. Survey and List of Parameters

### 11.1 Explanation of Parameter Survey

The parameter survey is designed as an aid for finding parameters quickly. It is a summary of references for the parameter list. Listed behind each reference are all parameters which exert an influence on the function described by the reference.

The parameter survey is divided into five columns:

Column 1 shows the references (functions) to which parameters are assigned.

Column 2 shows the abbreviations of the respective functions.

Column 3 shows all parameters (setting numbers) belonging to the respective reference.

Column 4 shows, for each function (reference) which controls inputs or outputs, the applicable indications such as Ex or Ax which can also be found on the connections diagram.

Column 5 shows, for each function (control inputs (Ex) or control outputs (Ax)), the respective plugs with the number of contacts (see connections diagram).

Example for searching a parameter:

Keyword (function): inverse rotation

The parameter survey shows in column 3 the parameter numbers 618, 623, 801.

Suppose that the inverse rotation function is to be enabled. The parameter list shows this function under parameter number 618.

### 11.2 Explanation of Parameter List

The parameter list is divided into 5 columns. These comprise, in

column 1: the parameter number,

column 2: is the explanation (meaning) of the parameters and the coding system of row 1 of the keys of the mini operator's panel, used when the parameter concerned can be programmed with the mini operator's panel,

column 3: the programming level (A, B, C) on which the parameter in question can be accessed,

column 4: the range of values within which the parameter in question can be set,

column 5: the value of the parameter in question is set on delivery ex factory.

Parameters having "either/or" validity (software switches) can merely be set to value I or II. In the case of such parameters, column 4 is empty.

Parameter numbers in acute brackets; e.g. <105>, mean the value (content) set for the parameter in question.

Example:

**107** Speed for front backtack when <106> = I

I limited by <105>

II limited by <607>

Explanation:

Parameter 107 is valid only the the value (content) of parameter <106> = I.

If parameter 107 is set to I (<107> = I), then the speed for the front backtack is limited by parameter 105, e.g. <105> = 1500. If parameter 107 is set to II (<107> = II), then the speed for the front backtack is limited by the value of parameter 607, e.g. <607> = 4000.

### 11.3 Parameter survey QP40SE (2Z\_X01\_4.HEX)

Function	Abbrev'n	Parameter	Input Output	Connection Socket/Contacts
Accelerate	DRZAN	722		
Affichage	ANZ	605		
Backtack	RIE	104/105/110 523		
Backtack inversion	RIV	419		
Backtack suppression	RIUNT	419		
Blower	BLA	668		
Brake	DRZAB	723/851		
Chopper	MESSER	105/110		
Control	REG	884/885/886 887/889/890 891/894		
Decorative backtack	ZRIE	522/523/530 775		
Defect search	HWT	797		
Delay	VERZ	623/641/730 731/732/739 740		
Direction of rotation	DRR	800		
Display	ANZ	605		
End backtack	ER	110/149/604 731/732/740		
Engine	MOT	897		
Feed reverse	TUM	721	E1 A5	X5:3 X4:4
Front backtack	AR	104/105/148 739		
Hardware test	HWT	797		
Inverse rotation	RDR	618/623/801		
Machine class	MAKL	799		
Needle bar	NASTA	987		
Needle position	NAPO	522/700/701 702/703/705 706/710		

Needle position change-over	NPW	616	E2	X1:1
Needle up without trimming	NHOS	616/710		
ON period	EINZ	715/889		
Photocell	LS	641		
Presser foot	PF	624/651/719 729/730	A4	X4:5
Program	PR	221/851		
Programming level C	EBC	798		
Repeat backtack	WRIE	731/740		
Residual brake	STBR	718		
Seam end	NE	110		
Seam start	NA	105		
Soft start	SANL	116/117		
Speed	DRZ	105/110/117 221/530/605 606/607/608 609/676/850 901		
Speed control unit	SWG	378		
Speed decrease	DRZAB	723/851		
Speed increase	DRZAN	722		
Speed limitation	DB	221/676		
Start	START	378/603/641 662	E3	X1:3
Start delay	STVERZ	729		
Starting block	ANLSP	624/665		
Stitch condensation	STVD	105/110/419 739		
Stop	STOP	624/665	E4	X4:3
Stop time	STOPZ	775		
Target stitch	PEIPO	653/789		
Thread puller	FZ	761		
Thread tension release	FSL	761		
Thread trimming	SN	601/604/609 705/706/732 901		

Thread wiper	WI	668/715	A3	X3:5
Time needed to switch on	EINZ	715/889		
Timing output	TA	719/721		
Vacuum	SAUG	105/110		

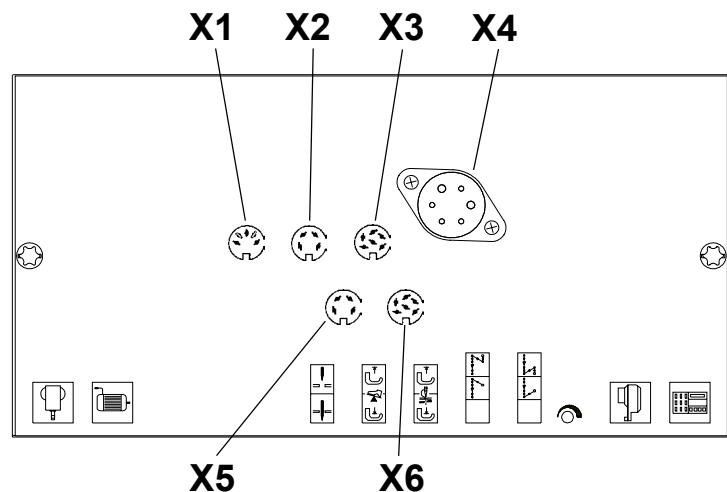
## 11.4 List of Parameters QP40SE (2Z\_X01\_4.HEX)

No.	Function (Meaning)	Level	Range Values	of Value	Standard
104	(AR/RIE) Front backtack correction (delayed disabling of feed reverse)	B,C	0 - 16	8	Kl. 1
105	(AR/RIE/DRZ/MESSER/NA/SAUG/STVD) Speed for front backtack / stitch condensation (00000011)	B,C	100 - 6400	1200	Kl. 1
110	(ER/RIE/DRZ/MESSER/NE/SAUG/STVD) Speed for end backtack / stitch condensation	B,C	100 - 6400	1200	Kl. 1
116	(SANL) Soft start stitches (00000111)	A,B,C	0 - 255	0	Kl. 1
117	(SANL/DRZ) Speed for soft start stitches	B,C	30 - 640	400	Kl. 1
148	(AR) Front backtack I double II single	A,B,C		I	Kl. 1
149	(ER) End backtack I double II single	A,B,C		I	Kl. 1
221	(PR/DB/DRZ) Speed limitation for sewing program 1 (or for all sewing programs)	B,C	300 - 6400	1200	Kl. 1
378	(START/SWG) Start erfolgt mit I Sollwertgeber II Eingangssignal „Ex“	B,C		I	Kl. 1
419	(RIV/RIUNT/STVD) Function of external key I backtack / stitch condensation inversion II backtack / stitch condensation suppression (flip-flop function)	B,C		I	Kl. 1
522	(NAPO/ZRIE) Needle position when stop occurs during decorative backtack (stitch in stitch) I position 2 (up) II position 1 (down) (00001101)	B,C		II	Kl. 1
523	(RIE/ZRIE) Backtack I decorative backtack (stitch in stitch) II standard backtack	A,B,C		I	Kl. 1
530	(DRZ/ZRIE) Speed (max.) for decorative backtack (00001111)	B,C	100 - 6400	1000	Kl. 1
601	(SN) Trimming I yes II no	B,C		I	Kl. 1
603	(START) Start after seam end I after treadle 0 only II immediate start of operation	B,C		I	Kl. 1
604	(SN/ER) Trimming after single end backtack I forward II backward	B,C		I	Kl. 1
605	(DRZ/ANZ) Actual speed in display I yes II no	B,C		II	Kl. 1
606	(DRZ) Speed: level 1 (min.) (00010001)	B,C	30 - 640	180	Kl. 1
607	(DRZ) Speed: level 12 (max.)	B,C	100 - 10000	1200	Kl. 1
608	(DRZ) Speed level curve (treadle characteristic) I linear II not linear	B,C		I	Kl. 1
609	(SN/DRZ) Trimming speed 1 (00010011)	B,C	30 - 300	180	Kl. 1
616	(NPW/NHOS) Function of external key (input E2) I needle position change-over (NPW) II needle up without trimming (NHOS)	B,C		II	Kl. 1

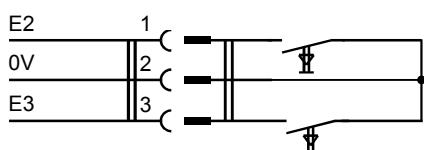
618	(RDR) Inverse rotation after seam end I yes II no	B,C		II	Kl. 1
623	(RDR/VERZ) Delay in start-up time (ms) for inverse rotation	B,C	0 - 2550	10	Kl. 1
624	(ANLSP/STOP/PF) Function of external key (input E4) I stop / safety switch no run II presser foot	B,C		II	Kl. 1
641	(LS/START/VERZ) Delay before start (ms) after photocell (at <640> = I)	B,C	0 - 2550	120	Kl. 1
651	(PF) Presser foot with automatic descent on machine stop I yes II no	B,C		II	Kl. 1
653	(PEIPO) Target stitch before sewing I yes II no	B,C		II	Kl. 1
662	(START) Key „start“ I active low (close) II active high (open)	B,C		I	Kl. 1
665	(ANLSP/STOP) Run locking/stop I contact closed II contact open	C		I	Kl. 1
668	(BLA/WI) Thread wiper/thread clearer I yes II no (00010101)	B,C		I	Kl. 1
676	(DRZ/DB) Speed adjustment via potentiometer possible I yes II no	B,C		I	Kl. 1
700	(NAPO) Needle position 0 (reference position of the needle)	B,C	0 - 239	0	Kl. 1
701	(NAPO) Angular adjustment I with handwheel (teach-in) II by keys (+/-)	B,C		I	Kl. 1
702	(NAPO) Needle position 1 (needle down) (00010111)	B,C	0 - 239	75	Kl. 1
703	(NAPO) Needle position 2 (thread take-up lever up)	B,C	0 - 239	213	Kl. 1
705	(NAPO/SN) Needle position 5 (end of trimming signal 1) (00011001)	B,C	0 - 239	125	Kl. 1
706	(NAPO/SN) Needle position 6 (start trimming signal 2)	B,C	0 - 239	119	Kl. 1
710	(NAPO/NHOS) Needle position 3 (needle up) (00011011)	B,C	0 - 239	200	Kl. 1
715	(EINZ/WI) Duration (ms) of thread wiper	B,C	0 - 2550	120	Kl. 1
718	(STBR) Timing of residual brake (0 = brake off)	B,C	0 - 100	0	Kl. 1
719	(PF/TA) Timing output A4 (0 = 100% switching on)	B,C	0 - 100	40	Kl. 1
721	(TUM/TA) Timing output A5 (0 = 100% switching on)	B,C	0 - 100	40	Kl. 1
722	(DRZAN) Acceleration ramp 1 gradual 50 steep	B,C	1 - 50	40	Kl. 1
723	(DRZAB) Brake ramp 1 gradual 50 steep	B,C	1 - 50	31	Kl. 1
729	(STVERZ/PF) Start delay after lowering presser foot	B,C	0 - 2550	120	Kl. 1
730	(PF/VERZ) Lift delay for presser foot after seam end	B,C	0 - 2550	50	Kl. 1

731	(ER/WRIE/VERZ) Delay before stitch counting for end backtack (ERV)	B,C	0 - 2550	40	KI. 1
732	(SN/ER/VERZ) Delay (ms) for trimming after single end backtack	B,C	0 - 2550	30	KI. 1
739	(AR/STVD/VERZ) Delay (ms) for speed after front backtack / stitch condensation	B,C	0 - 2550	120	KI. 1
740	(ER/WRIE/VERZ) Delay before stitch counting for end backtack backward	B,C	0 - 2550	0	KI. 1
761	(FSL/FZ) Prolongation Thread tension release/ Thread puller	B,C	0 - 2550	0	KI. 1
775	(ZRIE/STOPZ) Stop time (ms) with stitch in stitch backtack (decorative backtack)	B,C	0 - 2550	100	KI. 1
789	(PEIPO) Needle position 10 (target stitch)	B,C	0 - 239	225	KI. 1
797	(HTW) Hardware test	B,C		II	KI. 1
I	yes				
II	no				
798	(EBC) Programming level C	B,C		II	KI. 1
I	yes				
II	no				
799	(MAKL) Machine class which has been selected (00011101)	C	1 - 1	1	KI. 1
800	(DRR) Direction of motor rotation viewed from belt pulley	B,C		II	KI. 1
I	left-hand rotation				
II	right-hand rotation				
801	(RDR) Reverse rotation angle after seam end	B,C	5 - 200	30	KI. 1
850	(DRZ) Maximum motor speed	C		4500	KI. 1
851	(PR/DRZAB) Brake ramp for stitch-count seams	C		I	KI. 1
I	steep				
II	gradual				
884	(REG) Proportional amplification of the speed control (in general)	B,C	4 - 50	12	KI. 1
885	(REG) Integral amplification of the speed control	C	0 - 100	30	KI. 1
886	(REG) Proportional amplification of the order controllers	C	1 - 50	20	KI. 1
887	(REG) Differential amplification of the order controllers	C	1 - 100	30	KI. 1
889	(EINZ/REG) Time required for order controlling (0 = always)	C	0 - 1000	400	KI. 1
890	(REG) Proportional amplification of the superior order controllers for the residual brake	C	1 - 50	25	KI. 1
891	(REG) Proportional amplification of the lower speed controllers for the residual brake	C	1 - 50	20	KI. 1
894	(REG) Rotational direction of motor and synchronizer	C		I	KI. 1
I	different				
II	same				
897	(MOT) MINI motor version	C		II	KI. 1
I	long				
II	short				
898	(SONST) Number of motor poles	C		II	KI. 1
I	4 poles				
II	6 poles				
901	(DRZ/SN) Trimming release speed	C	30 - 500	300	KI. 1
933	(SONST) Display change-over	A,B,C		I	KI. 1
I	diagnosis				
II	normal display				
987	(NASTA) Switch-off position for needle bars	C		I	KI. 1

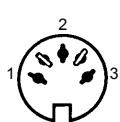
## 12. Electrical Connections Diagram QP40SE



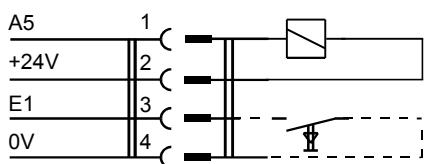
**X1**



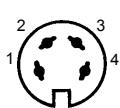
**S2**  
**S3**



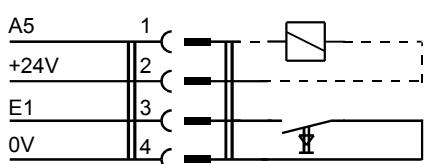
**X2**



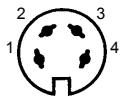
**Y5**  
**S1**



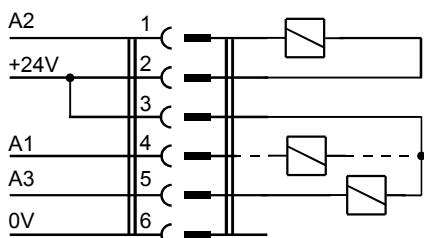
**X5**



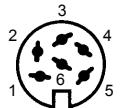
**Y5**  
**S1**



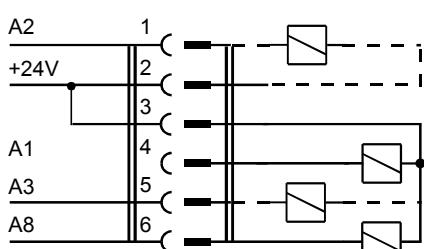
**X3**



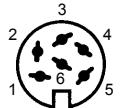
**Y2**  
**Y1**  
**Y3**



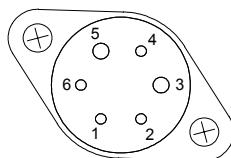
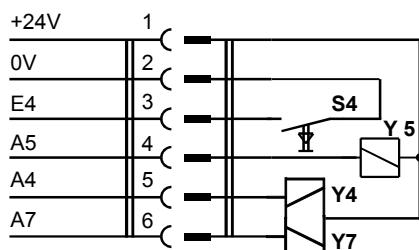
**X6**



**Y2**  
**Y1**  
**Y3**  
**Y8**



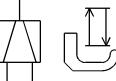
## X4



Bedeutung der Magnete bzw. Magnetventile, Taster / Meaning of magnets and/or solenoids and keys  
 Signification des aimants resp. solenoides et touches / Significação dos imãs e/ou as solenoidas e teclas  
 Significato dei magneti, delle valvole magnetiche e dei tasti / Significación de los imanes y/o los solenoides y pulsadores / Betekenis van de magneten resp. magneetkleppen, toetsen

<b>S1</b>		Transportumstellung von Hand / manual feed reverse / renversement de marche manuel / mudança do transporte manual / commutazione trasporto a mano / inversión de transporte manual / handmatige transportomschakeling
<b>S2</b>		<616> = I: Nadelpositionswechsel / needle position change-over / changement de position d'aiguille / troça de posição da agulha / cambio di posizione dell'ago / cambio de posición de aguja / naaldpositie-verwisseling
<b>S2</b>		<616> = II: Nadel hoch ohne Schneiden / needle up without thread trimming / aiguille en haut sans coupe / agulha para cima sem corte de linhas / ago su senza taglio / aguja arriba sin corte / naald omhoog zonder snijden
<b>S3</b>		Start / start / start / arranque / start / arranque / start
<b>S4</b>		<624> = I: STOP
<b>S4</b>		<624> = II: Presserfuß heben / lifting presser foot / relevage du pied presseur / levantar do calcador / sollevamento del alzapiedino / elevación de prensatelas / drukvoet optillen
<b>Y1</b> I max 10 A *		Fadenschneider pneumatisch / pneum. thread trimmer / coupe-fil pneumatique / corte de linhas pneumático / rasafilo pneumático / cortahilos neumático / draadsnijder pneumatisch
<b>Y2</b> I max 10 A *		Fadenschneider magnet. / magn. thread trimmer / coupe-fil magnétique / corte de linhas magnético / rasafilo magnético / cortahilos magnético / draadsnijder magnetisch
<b>Y3</b> I max 10 A *		Fadenwischer / thread wiper / écarteur de fil / retira-linhas / scartafilo / retirahilos / draadwisser

Bedeutung der Magnete bzw. Magnetventile, Taster / Meaning of magnets and/or solenoids and keys  
 Signification des aimants resp. solenoides et touches / Significação dos imãs e/ou as solenoidas e teclas  
 Significato dei magneti, delle valvole magnetiche e dei tasti / Significación de los imanes y/o los solenoides y pulsadores / Betekenis van de magneten resp. magneetkleppen, toetsen

<b>Y4/Y7</b> I max 10 A *	 <b>Y4:</b> Presserfuß heben / lifting presser foot / relevage du pied presseur / levantar do calcador / sollevamento del alzapiedino / elevación de prensatelas / drukvoet optillen <b>Y7:</b> Presserfuß senken / lowering presser foot / descente du pied presseur / baixar o calcador / abbassare del alzapiedino / bajar el prensatelas / drukvoet laten zakken
<b>Y5</b> I max 10 A *	 Transportumsteller / feed reverse / renversement de marche / mudança do transporte / commutazione trasporto / inversión de transporte / transportomschakeling
<b>Y8</b> I max 300 mA	 Maschinenlauf / motor runs / moteur en marche / motor em movimento / motore in moto / motor en marcha / loop van de machine

- \* Die Summe der Lastströme aller gleichzeitig eingeschalteten Stellglieder (Magnete, Magnetventile) darf den Wert von 4A nicht überschreiten (siehe hierzu Kapitel 2. Technische Daten).

The total of load currents of all servos activated simultaneously (solenoids, solenoid valves) is not allowed to exceed 4 amps (see also section 2. Technical Specifications).

Le total des courants de charge de tous les vérins (aimants, électro-vannes) activés simultanément ne doit pas dépasser 4 A (voir aussi le chapitre 2. "caractéristiques techniques").

A soma das correntes sob carga de todos os actuadores ligados ao mesmo tempo (ímans, solenóides) não pode ultrapassar o valor de 4A (ver também capítulo 2. Dados Técnicos).

La somma delle correnti di carico di tutti gli attuatori inseriti contemporaneamente (magneti, elettrovalvole) non deve essere superiore a 4 A (vedere il capitolo 2. Dati Tecnici).

La suma de las corrientes bajo carga de todos los elementos de todos los componentes de regulación conectados simultáneamente (imanes, válvula magnética) no podrá sobrepasar el valor de 4A (véase también el capítulo 2. de datos técnicos).

De belastingsstroom van alle tegelijkertijd ingeschakelde bedieningsschakels (magneten, magneetventielen) mag in totaal niet meer dan 4 A bedragen (zie hiervoor hoofdstuk 2. Technische gegevens).

## 13. Maintenance and Repair



!! Before starting maintenance or repair work, switch off the SERVO-TOP, separate the drive system from mains power (for instance by pulling out the mains plug) and wait for the motor to come to a complete stop.

General maintenance work must only be done by specially trained personnel paying close attention to the operating instructions.

The SERVO-TOP ist largely maintenance-free.

However, make sure to perform the following maintenance work:

Depending on the operating conditions, clean the drive system regularly, at least once a week, from any dust or lint. Make sure in particular that the ventilation louvres and cooling fins of the motor, especially the cooling fins between the motor and the control box, are perfectly clean (Fig. 13).

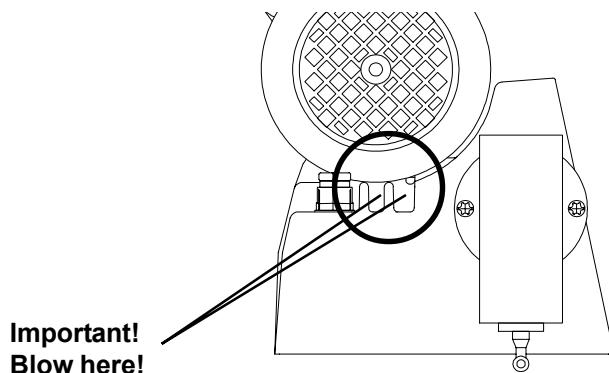


Fig. 13

Remove any threads caught on the synchronizer shaft or on the belt pulley and/or motor shaft.

Check if the drive system is perfectly secured to the stand and that the accessories (synchronizer on machine shaft, speed control unit on control box) are safely mounted in their respective positions.

Check the drive belt for any wear and for correct tension.  
Incorrect belt tension can increase noise and vibrations.



When opening covers or removing parts, apart from those removable by hand, live elements can be exposed.  
Connections can also be electrically live.

If you require to open the drive system before starting maintenance or repair work or before replacing any parts, disconnect the drive system from any and all power sources.

If maintenance or repair work on the open unit is unavoidable, this may only be done by qualified personnel familiar with the risks involved. Observe all regulations as per EN 50110.

There can still be capacitors carrying a charge in the power electronics system, even when the drive system has been disconnected from all power sources. To avoid injury by electrical shock, it is therefore essential to wait at least 10 minutes between mains power shutoff and opening the control box.

In order to protect semi-conductor components from overvoltage, use only high-resistivity measuring equipment when making checks on the control system.

Any repair or servicing work requiring skilled knowhow may only be done by qualified personnel authorized by Quick-Rotan.

We emphasize that in accordance with the product liability law we are under no responsibility for damages caused by our products if these are due to

- unqualified repair
- the use of components not authorized by us
- actions made by any persons not authorized by us.